

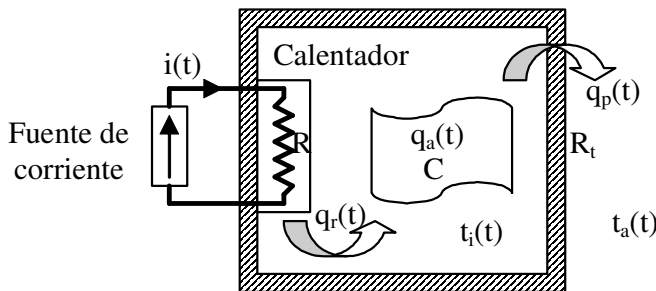
El sistema de la figura se modela mediante las ecuaciones:

$$\begin{aligned} q_r(t) &= q_a(t) + q_p(t) \\ q_r(t) &= R \cdot i^2(t) \\ q_a(t) &= C \cdot dt_i(t)/dt \\ q_p(t) &= (t_i(t) - t_a(t))/R_t \end{aligned}$$

Con los siguientes valores de los parámetros:

$$R=20 \Omega; C=4184 \text{ julio/}^\circ\text{C}; R_t=0.1 \text{ }^\circ\text{C} \cdot \text{s/julio}$$

Obtener las funciones de transferencia " $T_i(s)/I(s)$ " y " $T_i(s)/T_a(s)$ ", para el punto de funcionamiento dado por " $i_0=0.5 \text{ A}$ " y " $t_{a0}=19 \text{ }^\circ\text{C}$ ".



a) Pto de funcionamiento:

$$\begin{aligned} q_{r0} &= q_{a0} + q_{p0} \\ q_{r0} &= R i_0^2 \\ q_{a0} &= 0 \\ q_{p0} &= (t_{i0} - t_{a0})/R_t \end{aligned} \quad \left. \begin{aligned} i_0 &= 0,5 \\ t_{a0} &= 19 \\ R R_t i_0^2 &= t_{i0} - t_{a0} \\ 20 \cdot 0,1 \cdot 0,25 &= t_{i0} - 19 \Rightarrow t_{i0} = 19,5 \end{aligned} \right\} \quad q_{r0} = q_{p0} = 20 \cdot 0,25 = 5$$

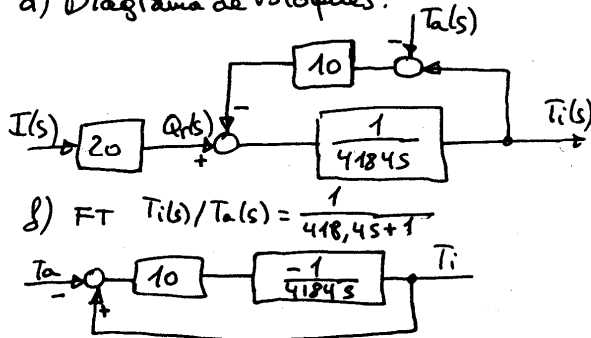
b) Linealización:

$$\begin{aligned} \Delta q_r(t) &= \Delta q_a(t) + \Delta q_p(t) \\ \Delta q_r(t) &= 2R i_0 \Delta i(t) = 20 \Delta i(t) \\ \Delta q_a(t) &= C \frac{d\Delta t_i(t)}{dt} = 4184 \frac{d\Delta t_i(t)}{dt} \\ \Delta q_p(t) &= 10 (\Delta t_i(t) - \Delta t_a(t)) \end{aligned}$$

c) Transformada de Laplace:

$$\begin{aligned} Q_r(s) &= Q_a(s) + Q_p(s) \\ Q_r(s) &= 20 I(s) \\ Q_a(s) &= 4184 \cdot s \cdot T_i(s) \\ Q_p(s) &= 10 (T_i(s) - T_a(s)) \end{aligned}$$

d) Diagrama de Bloques:



f) FT  $T_i(s)/T_a(s) = \frac{1}{418,45s + 1}$

e) FT  $T_i(s)/I(s) = \frac{2}{418,45s + 1}$

