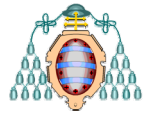


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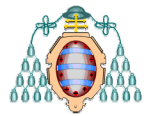
# Sensores

Sistemas Automáticos– Tema 14



# Contenidos

- ▶ Características de los sensores
- ▶ Límites de la medida
- ▶ Acondicionamiento de la señal
- ▶ Errores de la medida
- ▶ Derivas
- ▶ Respuesta dinámica

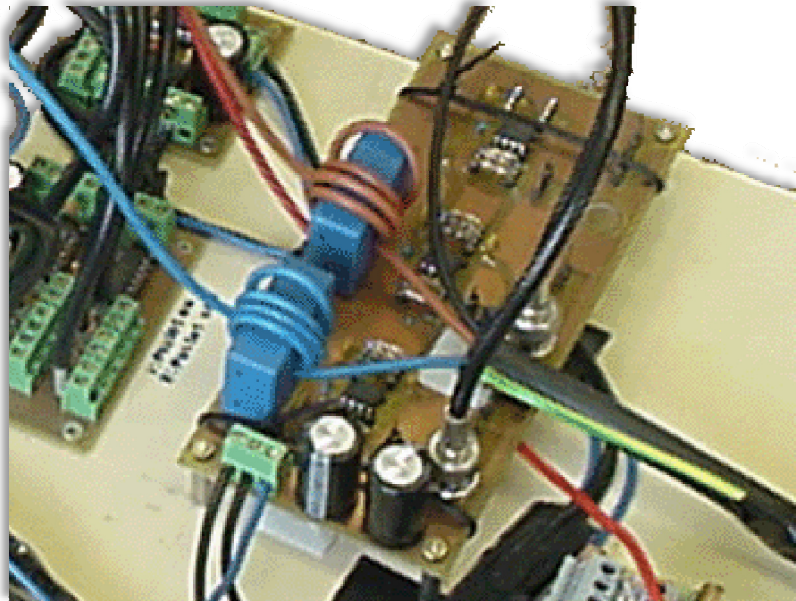


# Características de los sensores

## ▶ Dinámicas

Respuesta dinámica

Derivas (drift)



## ▶ Estáticas

Límites de la medida

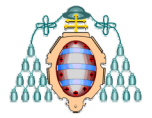
- Rango de medida (input span)
- Resolución (discrimination)

Acondicionamiento de la señal

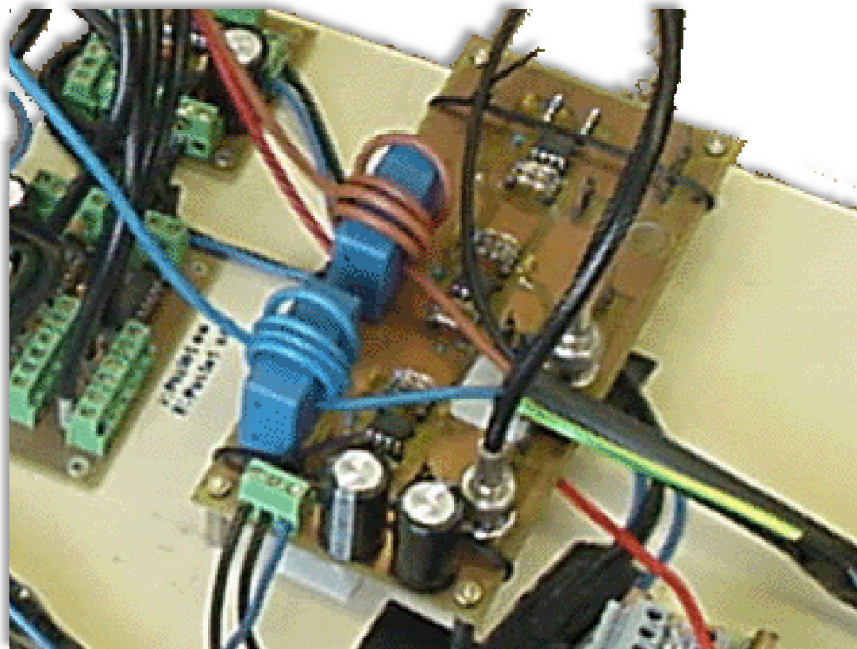
- Rango de salida (output span)
- Sensibilidad (sensitivity)

Errores de la medida

- Exactitud (accuracy)
- Precisión, repetitividad (precision)
- Linealidad (linearity)
- Histéresis (hysteresis)
- Offset



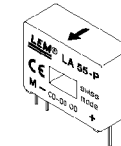
# Características de los sensores



## Current Transducer LA 55-P

$I_{PN} = 50 \text{ A}$

For the electronic measurement of currents : DC, AC, pulsed..., with a galvanic isolation between the primary circuit (high power) and the secondary circuit (electronic circuit).



### Electrical data

$I_{PN}$	Primary nominal r.m.s. current	50	A
$I_P$	Primary current, measuring range	0 .. $\pm 70$	A
$R_M$	Measuring resistance @	$T_A = 70^\circ\text{C}$	$T_A = 85^\circ\text{C}$
		$R_{M \min}$ $R_{M \max}$	$R_{M \min}$ $R_{M \max}$
	with $\pm 12 \text{ V}$	@ $\pm 50 \text{ A}_{\text{max}}$ 10 100	60 95 $\Omega$
		@ $\pm 70 \text{ A}_{\text{max}}$ 10 50	60 <sup>1)</sup> 60 <sup>1)</sup> $\Omega$
	with $\pm 15 \text{ V}$	@ $\pm 50 \text{ A}_{\text{max}}$ 50 160	135 155 $\Omega$
		@ $\pm 70 \text{ A}_{\text{max}}$ 50 90	135 <sup>2)</sup> 135 <sup>2)</sup> $\Omega$
$I_{SN}$	Secondary nominal r.m.s. current	50	mA
$K_N$	Conversion ratio	1 : 1000	
$V_C$	Supply voltage ( $\pm 5\%$ )	$\pm 12 \dots 15$	V
$I_C$	Current consumption	10 (@ $\pm 15 \text{ V}$ ) + $I_S$	mA
$V_d$	R.m.s. voltage for AC isolation test, 50 Hz, 1 mn	2.5	kV

### Features

- Closed loop (compensated) current transducer using the Hall effect
- Printed circuit board mounting
- Insulated plastic case recognized according to UL 94-V0.

### Advantages

- Excellent accuracy
- Very good linearity
- Low temperature drift
- Optimized response time
- Wide frequency bandwidth
- No insertion losses
- High immunity to external interference
- Current overload capability.

### Applications

- AC variable speed drives and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications.

### Accuracy - Dynamic performance data

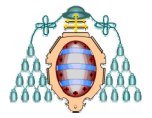
$X$	Accuracy @ $I_P, T_A = 25^\circ\text{C}$	@ $\pm 15 \text{ V}$ ( $\pm 5\%$ )	$\pm 0.65$	%
		@ $\pm 12 \dots 15 \text{ V}$ ( $\pm 5\%$ )	$\pm 0.90$	%
$\epsilon_L$	Linearity		< 0.15	%
$I_D$	Offset current @ $I_P = 0, T_A = 25^\circ\text{C}$	Typ	Max	mA
$I_{DM}$	Residual current <sup>3)</sup> @ $I_P = 0$ , after an overload of $3 \times I_{PN}$			mA
$I_{DT}$	Thermal drift of $I_D$	$0^\circ\text{C} \dots +70^\circ\text{C}$	$\pm 0.1$	$\pm 0.5$ mA
		$-25^\circ\text{C} \dots +85^\circ\text{C}$	$\pm 0.1$	$\pm 0.6$ mA
$t_a$	Reaction time @ 10% of $I_{P \max}$		< 500	ns
$t_r$	Response time @ 90% of $I_{P \max}$		< 1	$\mu\text{s}$
$di/dt$	$di/dt$ accurately followed		> 200	A/ $\mu\text{s}$
$f$	Frequency bandwidth (-1 dB)		DC .. 200	kHz

### General data

$T_A$	Ambient operating temperature	-25 .. +85	$^\circ\text{C}$
$T_S$	Ambient storage temperature	-40 .. +90	$^\circ\text{C}$
$R_S$	Secondary coil resistance @	$T_A = 70^\circ\text{C}$ 80	$\Omega$
		$T_A = 85^\circ\text{C}$ 85	$\Omega$
$m$	Mass	18	g
	Standards <sup>4)</sup>	EN 50178	

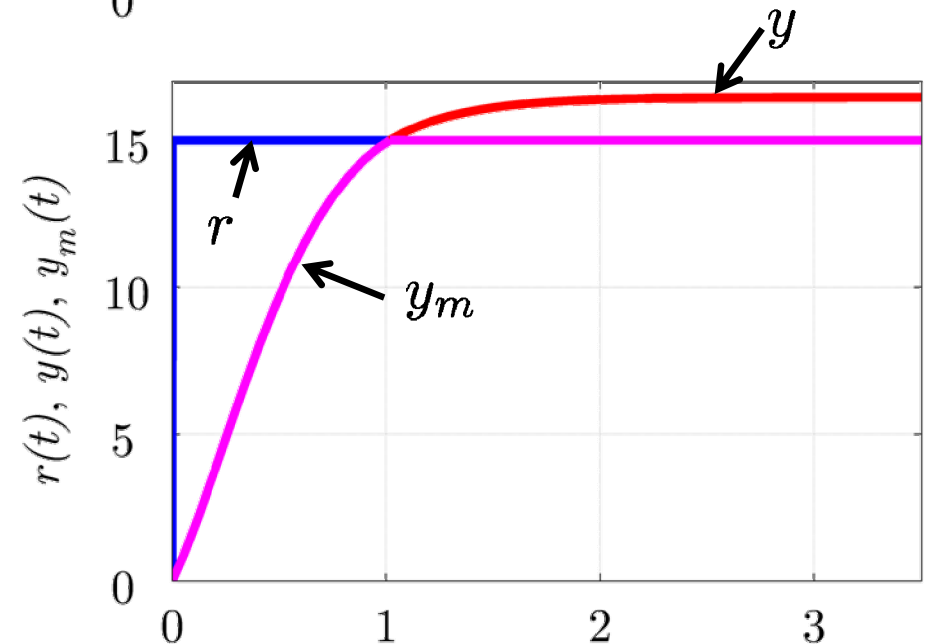
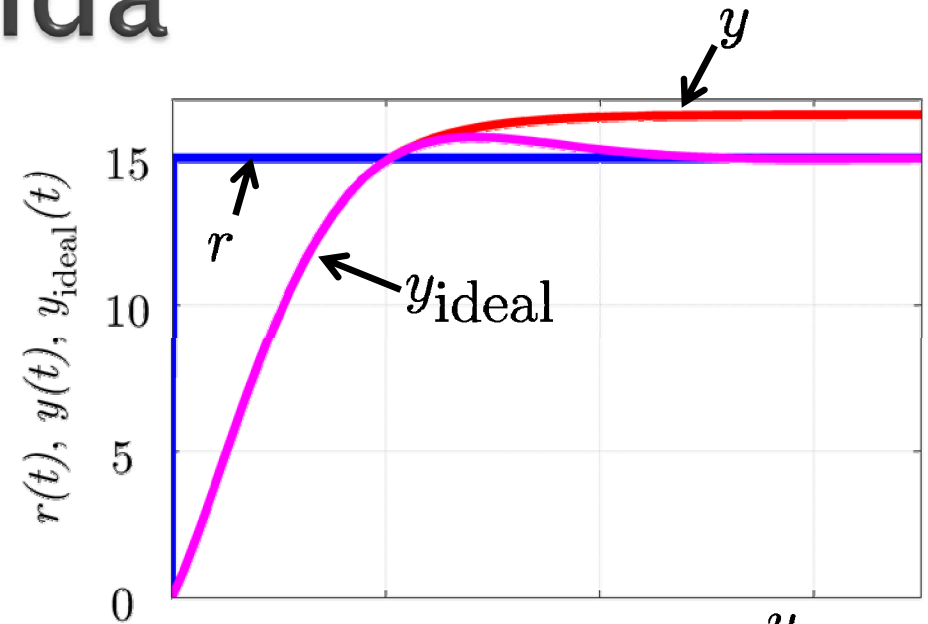
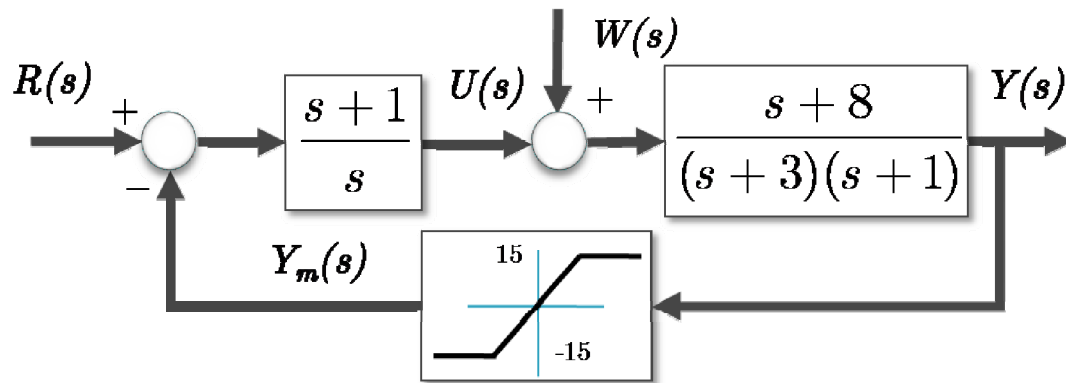
- Notes :**
- <sup>1)</sup> Measuring range limited to  $\pm 60 \text{ A}_{\text{max}}$
  - <sup>2)</sup> Measuring range limited to  $\pm 55 \text{ A}_{\text{max}}$
  - <sup>3)</sup> Result of the coercive field of the magnetic circuit
  - <sup>4)</sup> A list of corresponding tests is available

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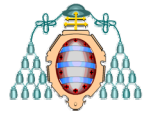
# Límites de la medida

## ► Rango de medida



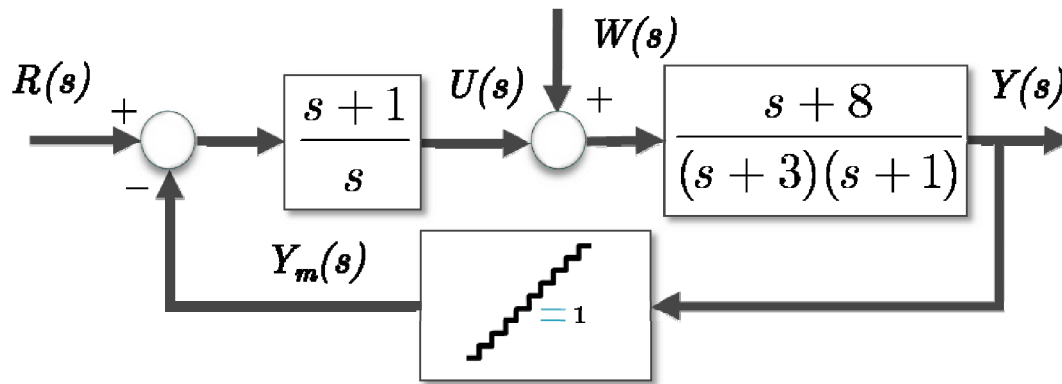
Electrical data						
$I_{PN}$	Primary nominal r.m.s. current		50			A
$I_P$	Primary current, measuring range		0 .. ± 70			A
$R_M$	Measuring resistance @		$T_A = 70^\circ\text{C}$		$T_A = 85^\circ\text{C}$	
			$R_{M \min}$	$R_{M \max}$	$R_{M \min}$	$R_{M \max}$
	with ± 12 V	@ ± 50 A <sub>max</sub>	10	100	60	95 Ω
		@ ± 70 A <sub>max</sub>	10	50	60 <sup>1)</sup>	60 <sup>1)</sup> Ω
	with ± 15 V	@ ± 50 A <sub>max</sub>	50	160	135	155 Ω
		@ ± 70 A <sub>max</sub>	50	90	135 <sup>2)</sup>	135 <sup>2)</sup> Ω

Tiempo (s)

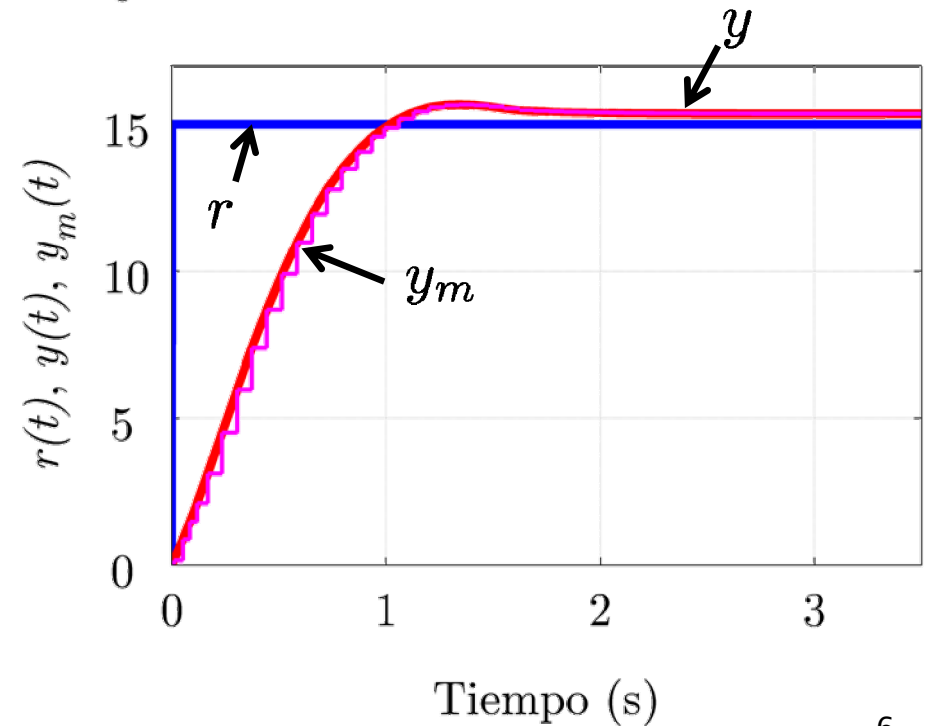
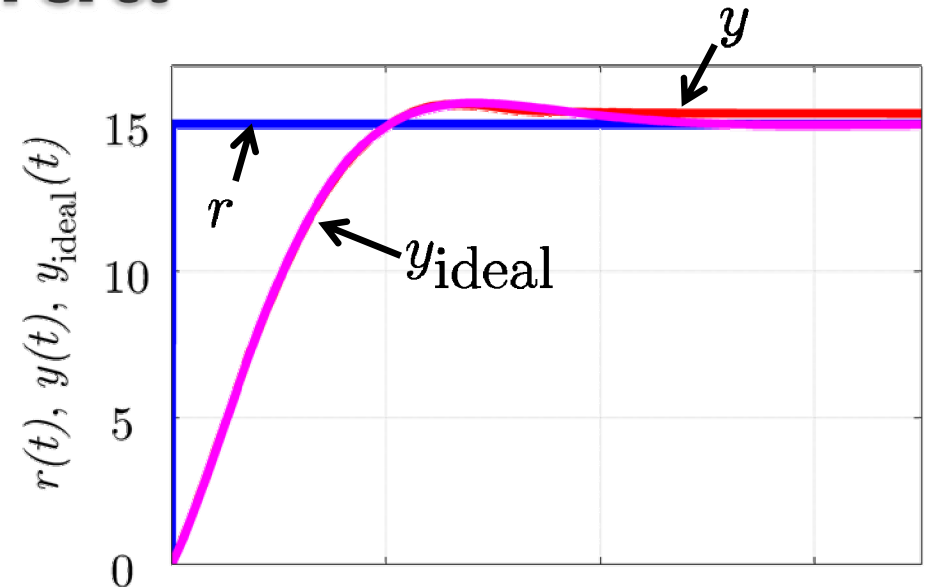


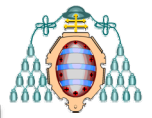
# Límites de la medida

## ► Resolución



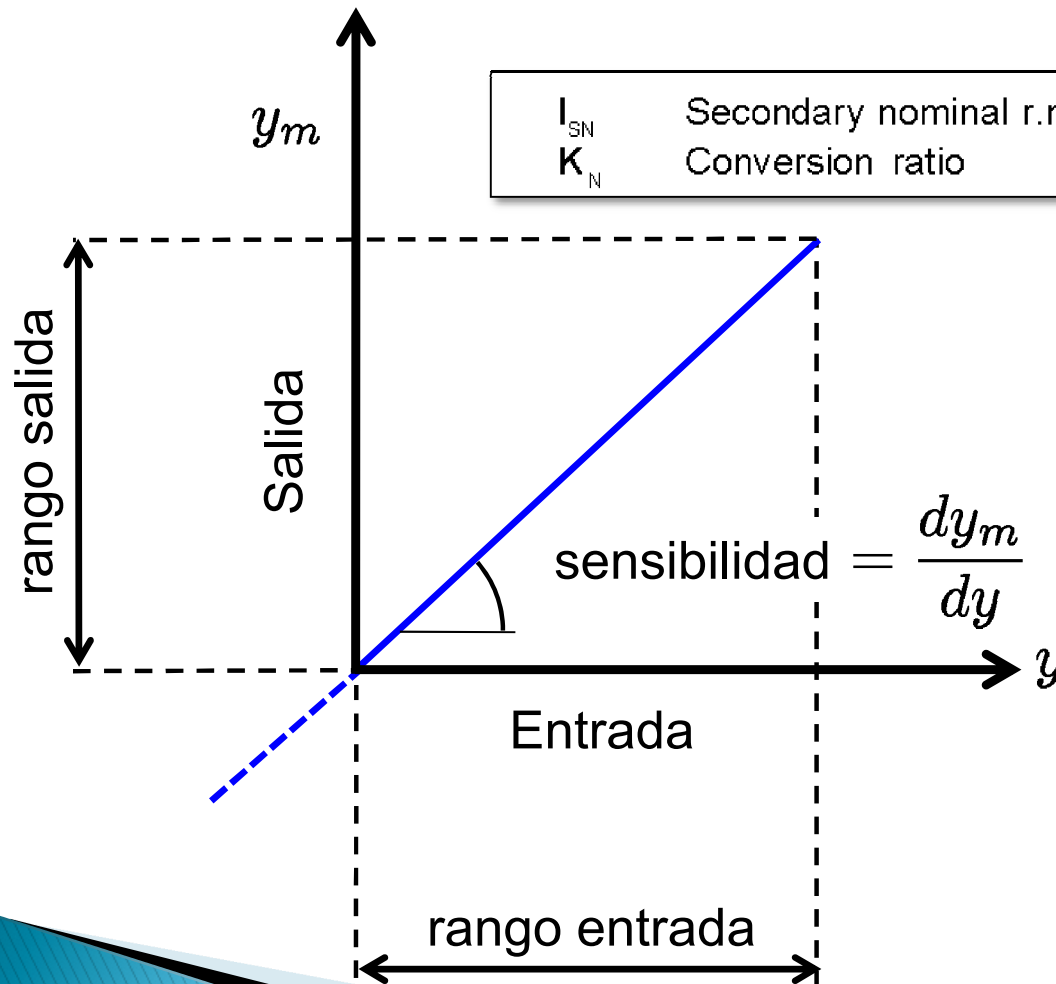
$$\text{error} \approx \frac{\text{resolución}}{2}$$



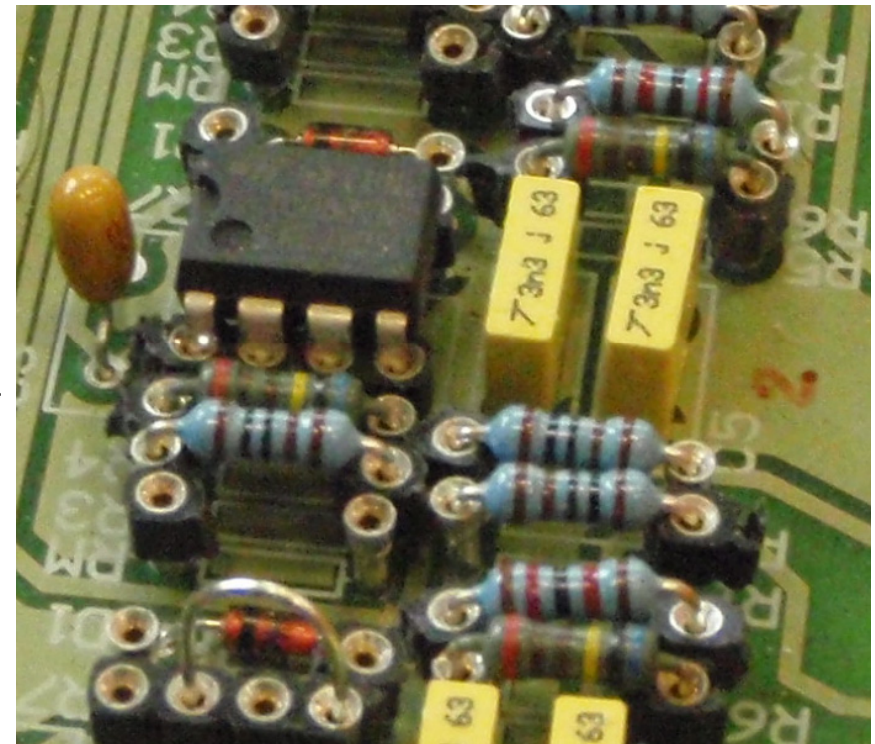


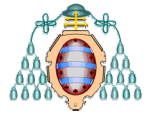
# Acondicionamiento de la señal

## ► Rango de salida y sensibilidad



$I_{SN}$	Secondary nominal r.m.s. current	50	mA
$K_N$	Conversion ratio	1 : 1000	

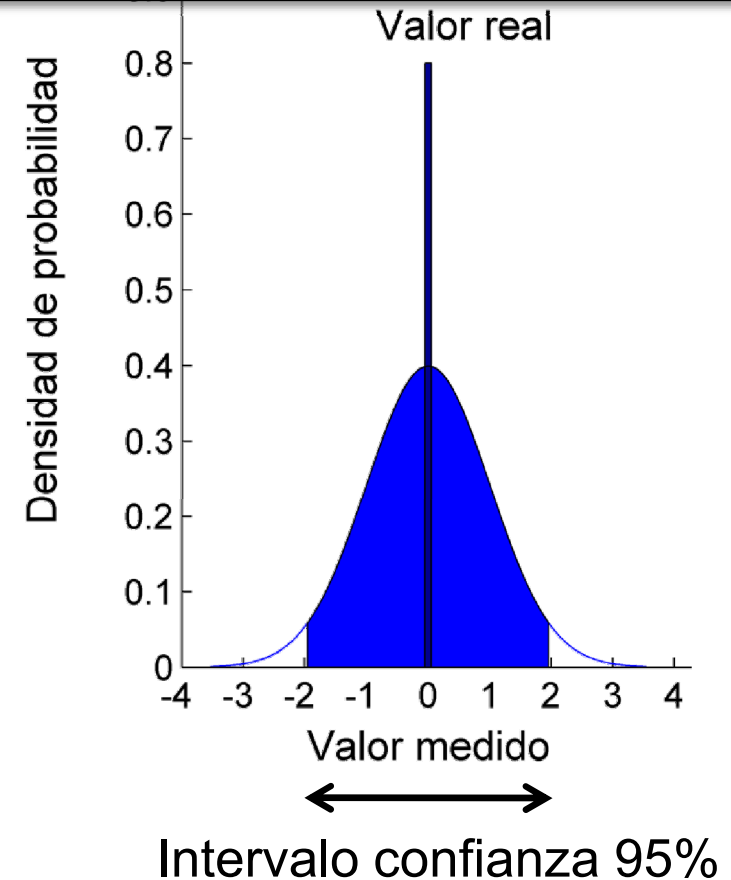
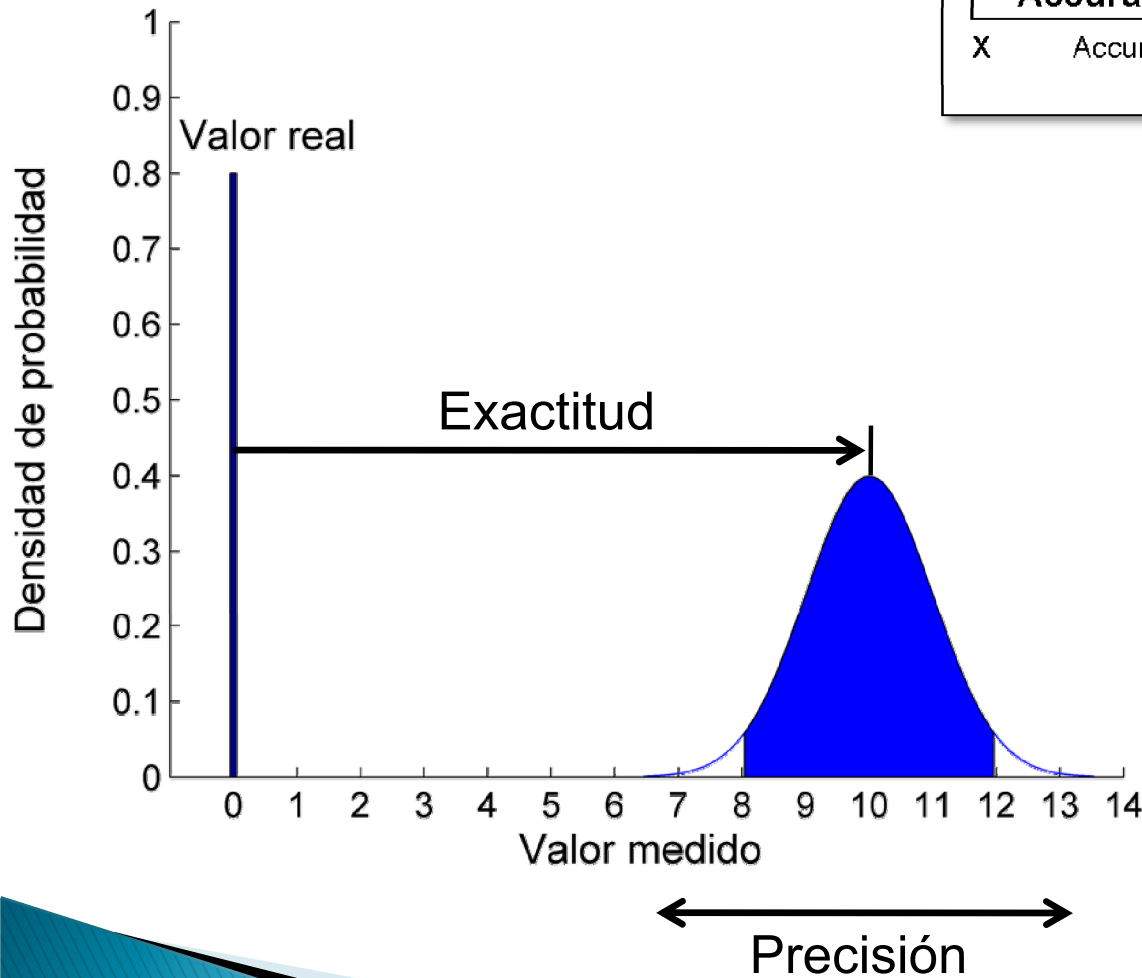




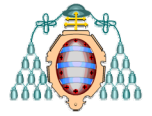
# Errores de la medida

## ▶ Exactitud y precisión

Accuracy - Dynamic performance data				
X	Accuracy @ $I_{PN}, T_A = 25^\circ\text{C}$	@ $\pm 15\text{ V } (\pm 5\%)$	$\pm 0.65$	%
		@ $\pm 12 \dots 15\text{ V } (\pm 5\%)$	$\pm 0.90$	%

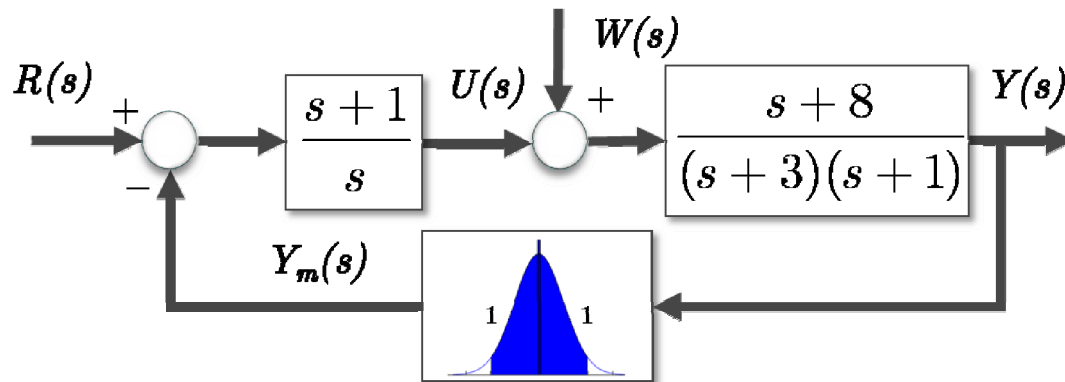




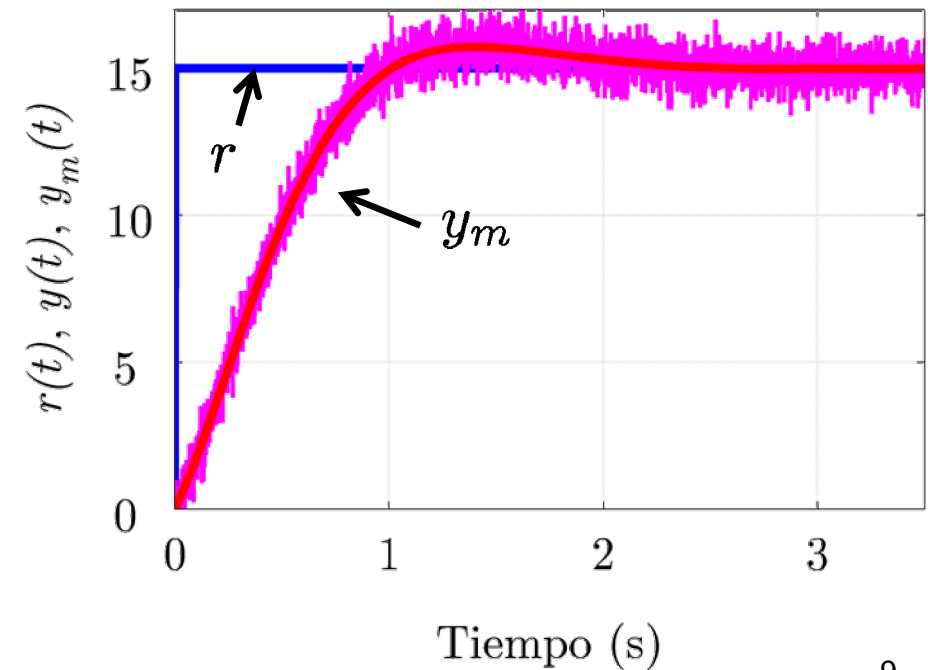
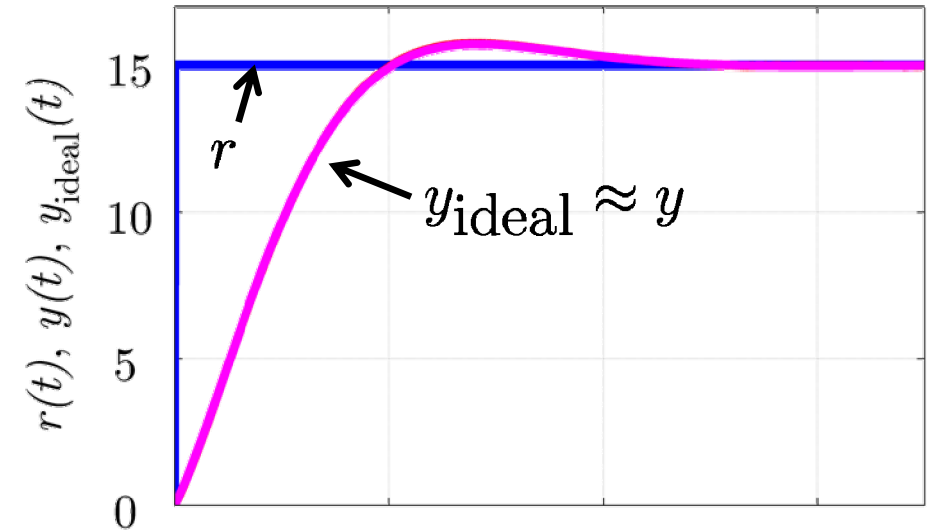


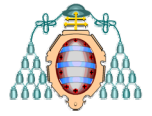
# Errores de la medida

## ► Precisión



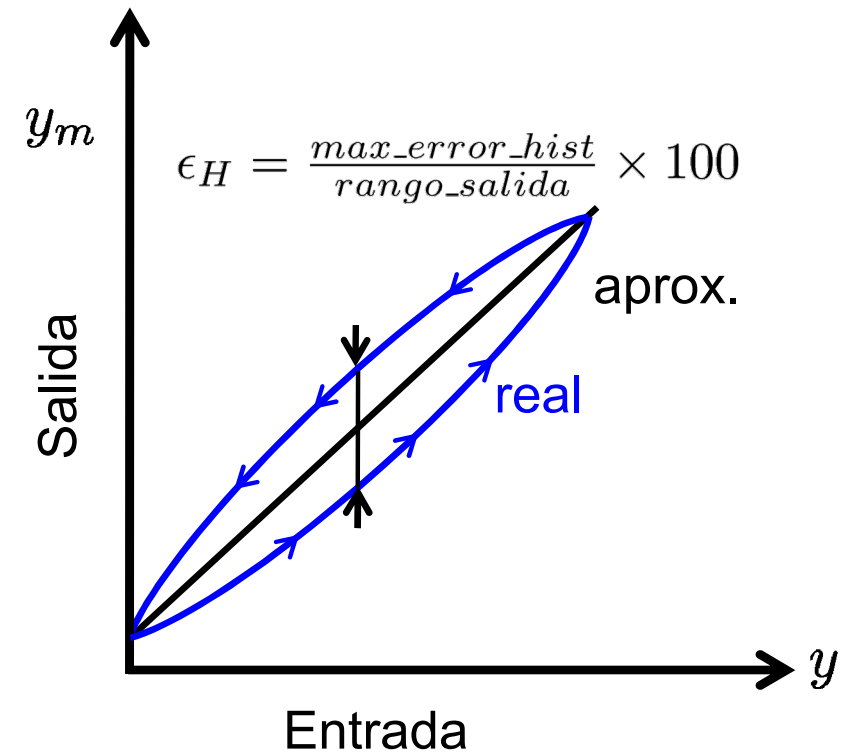
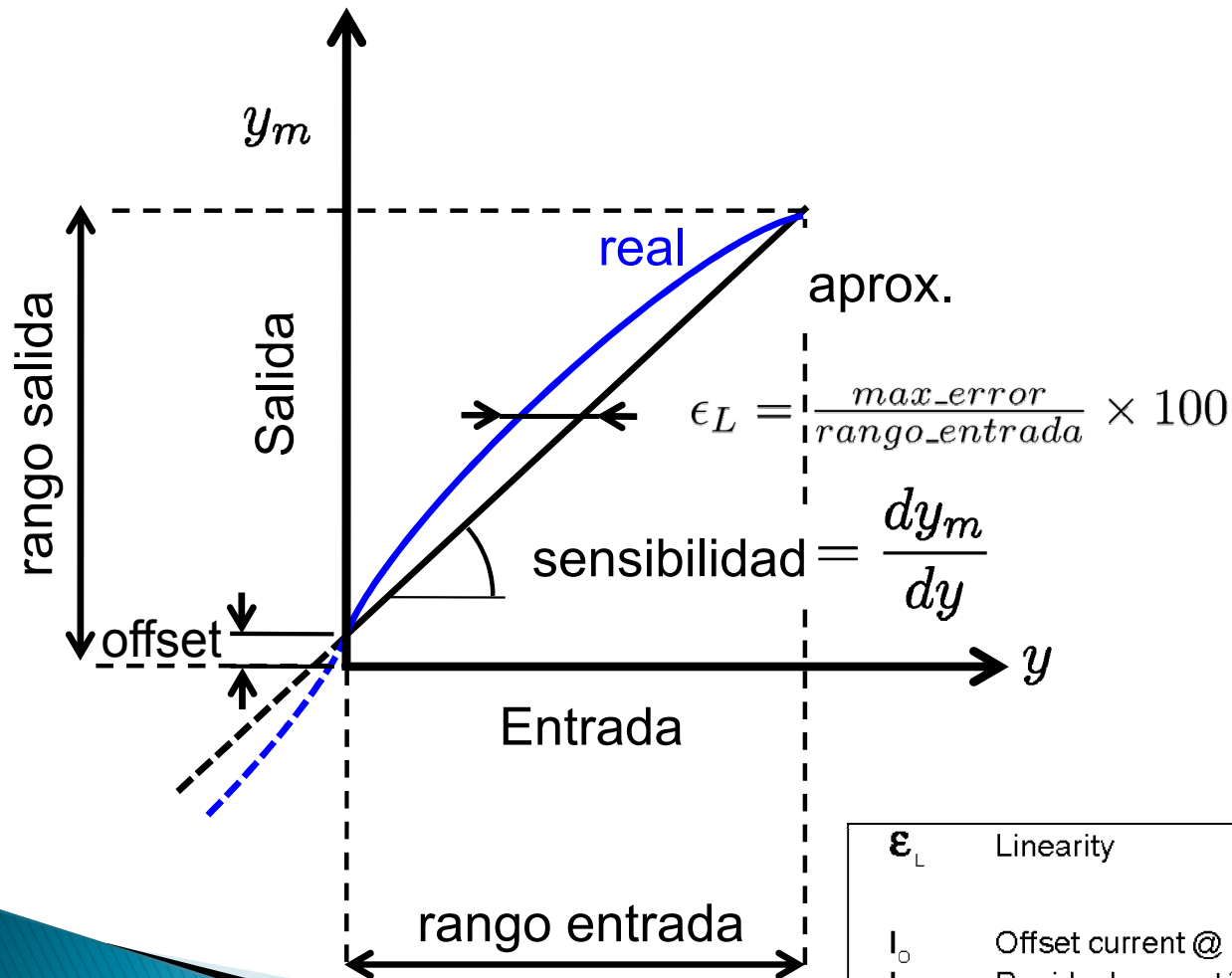
El efecto de la precisión se traduce en una fuente de ruido blanco gaussiano



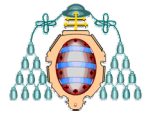


# Errores de la medida

## ▶ Linealidad, histéresis, offset

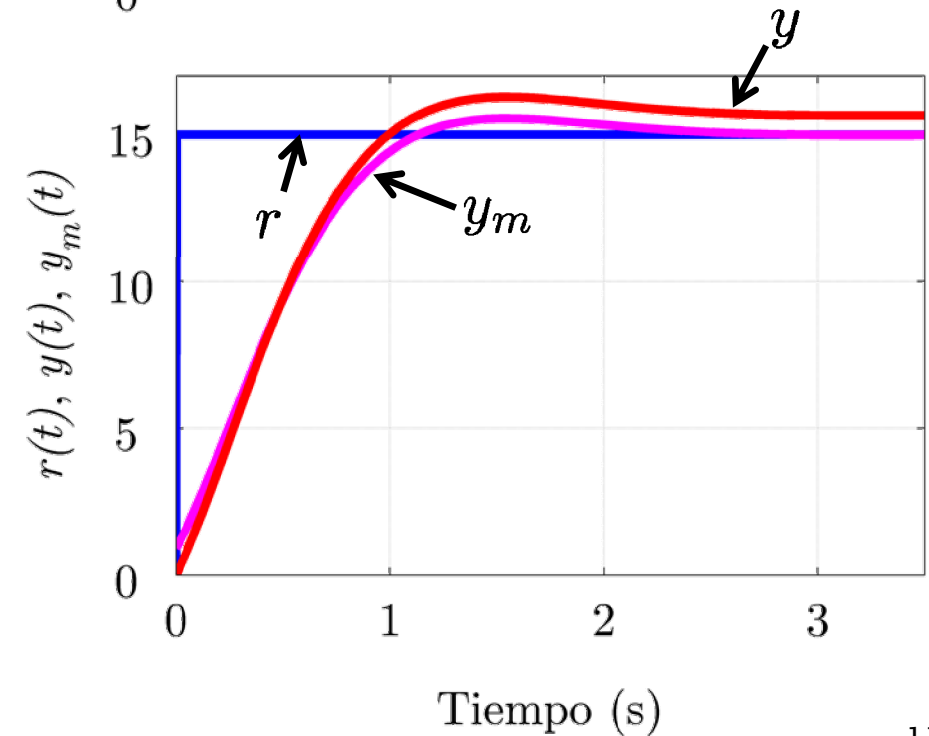
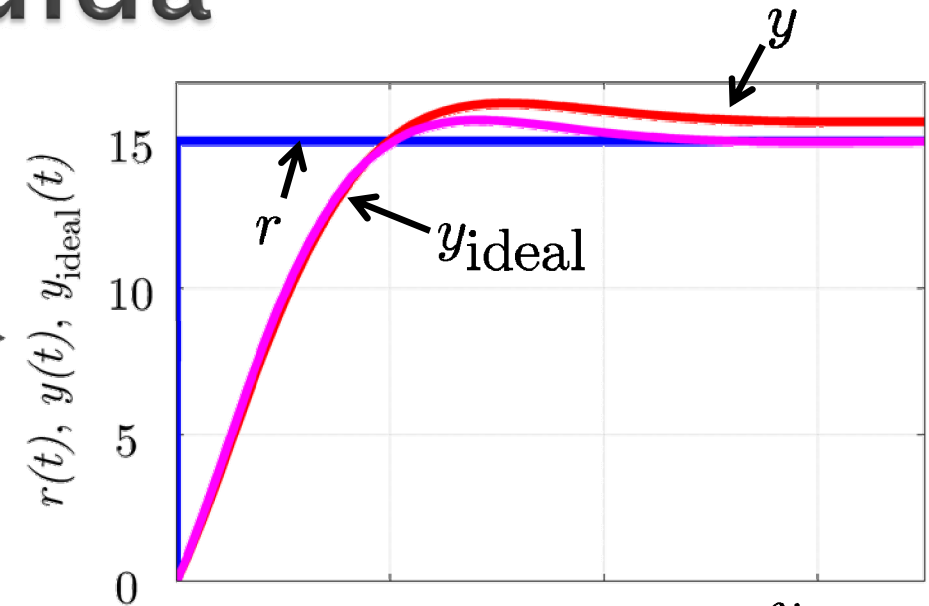
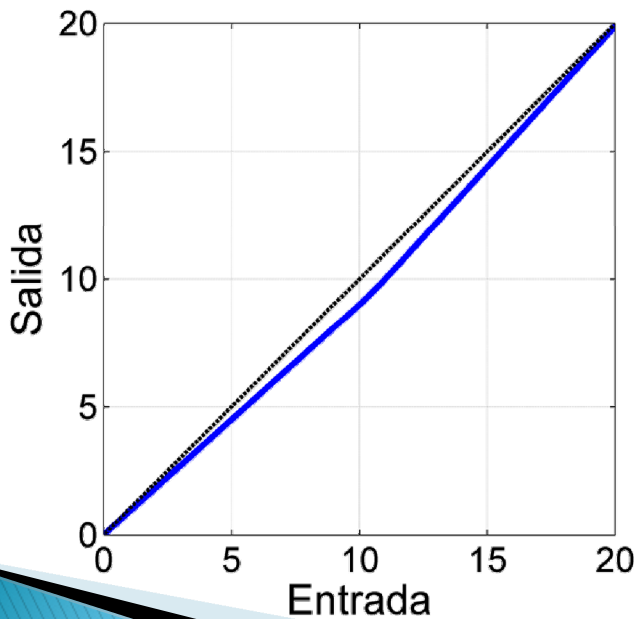
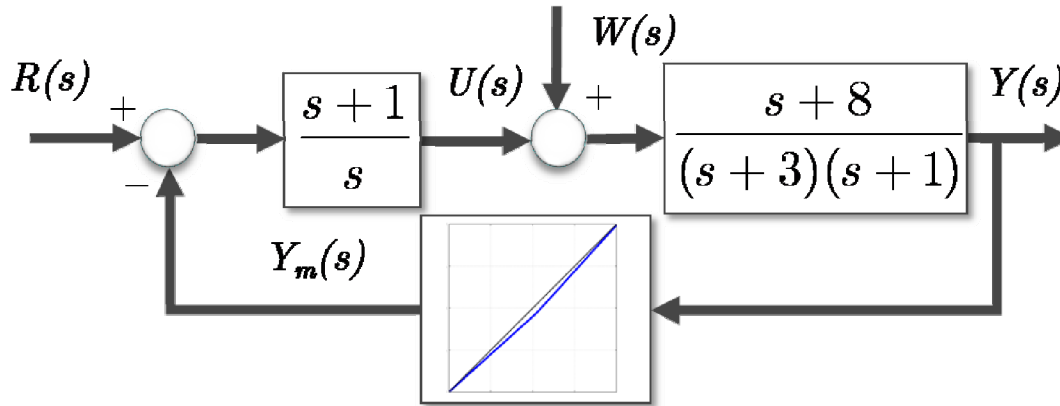


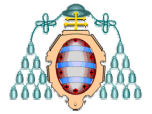
$\epsilon_L$	Linearity	< 0.15	%
$I_o$	Offset current @ $I_p = 0, T_A = 25^\circ\text{C}$	Typ	Max
$I_{QM}$	Residual current <sup>3)</sup> @ $I_p = 0$ , after an overload of $3 \times I_{PN}$		
		$\pm 0.2$	mA
		$\pm 0.3$	mA



# Errores de la medida

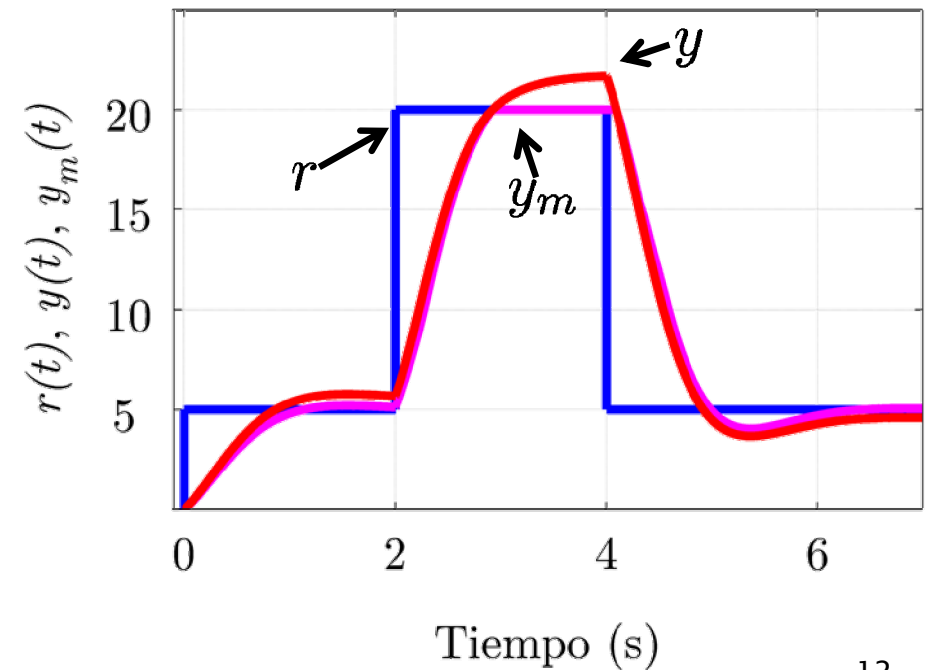
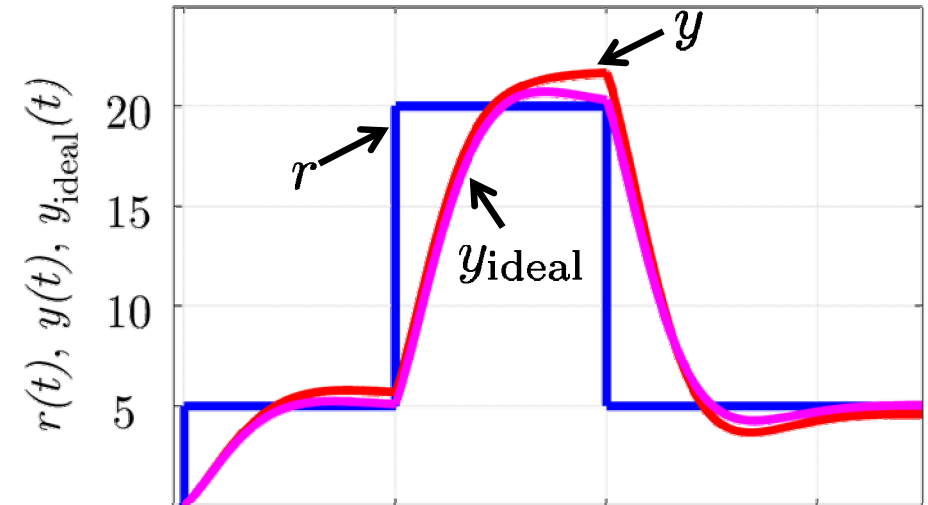
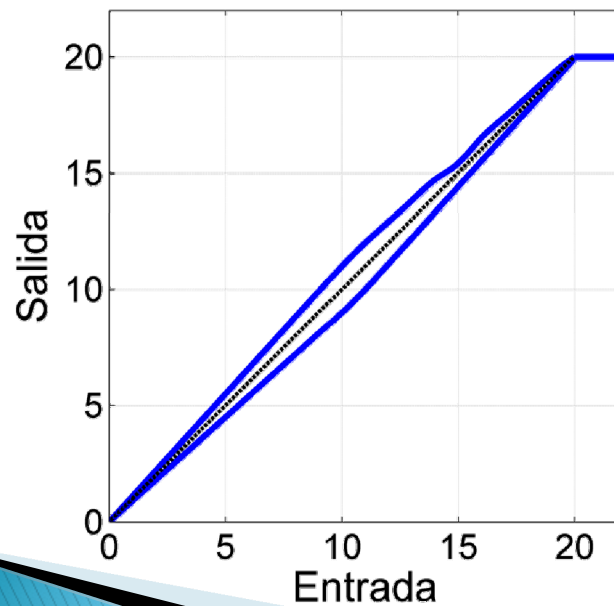
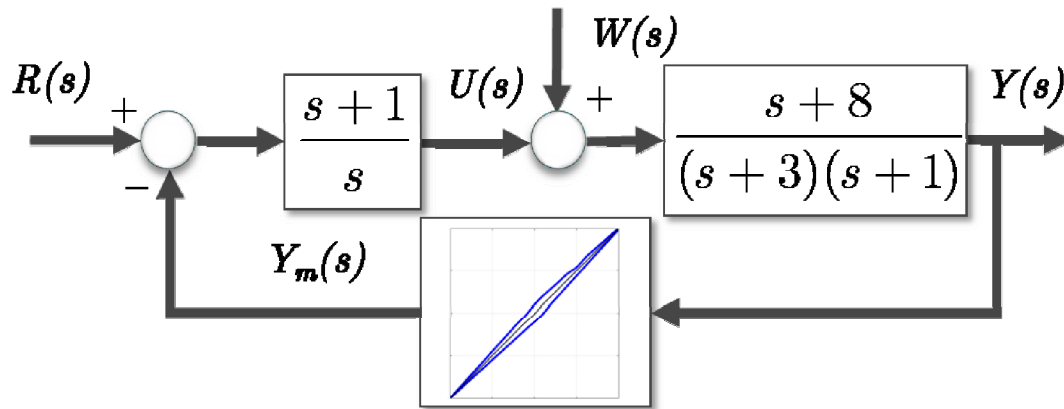
## ► Linealidad

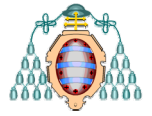




# Errores de la medida

## ► Histéresis





# Derivas

- ▶ Temperatura

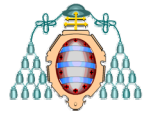
$I_{OT}$	Thermal drift of $I_o$	0°C .. + 70°C	± 0.1	± 0.5	mA
		- 25°C .. + 85°C	± 0.1	± 0.6	mA

- ▶ Envejecimiento (oxidación, desgaste)

- ▶ Humedad

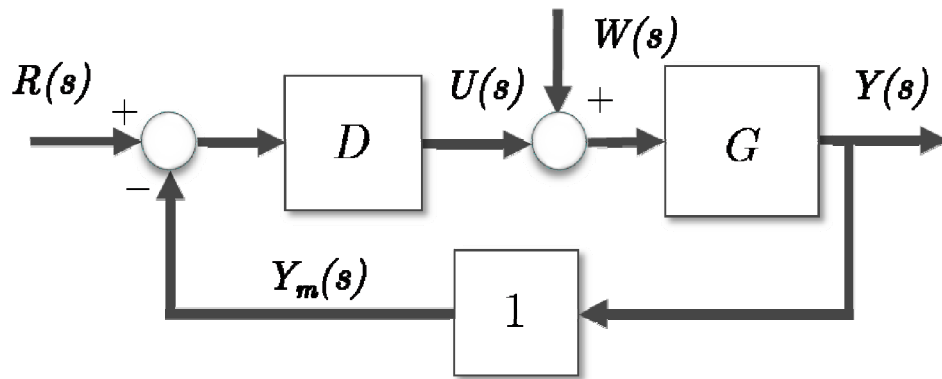
- ▶ Suciedad



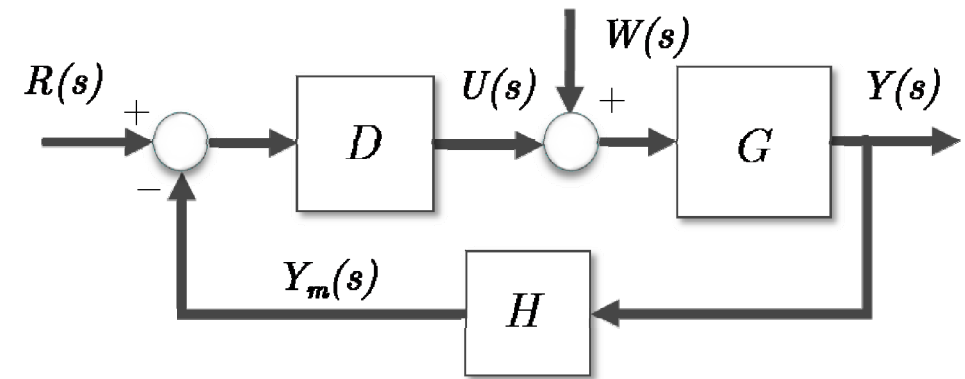


# Respuesta dinámica

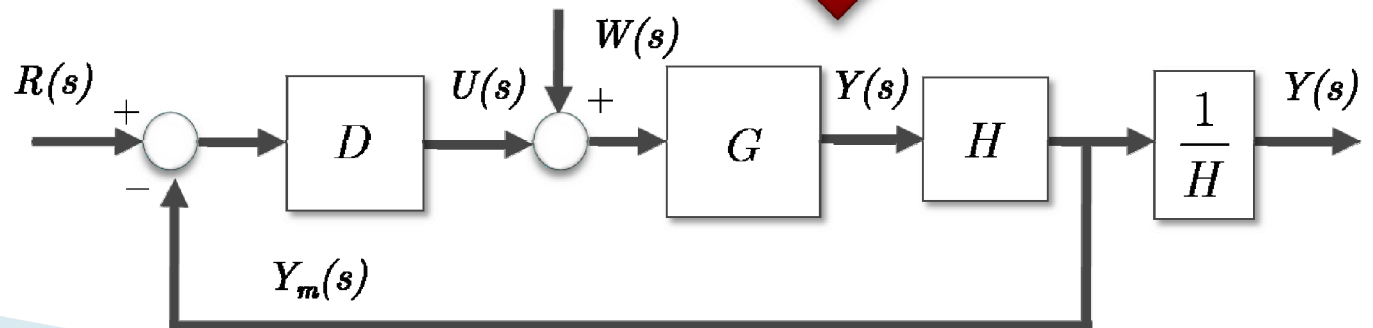
$t_{ra}$	Reaction time @ 10 % of $I_{P \max}$	< 500	ns
$t_r$	Response time @ 90 % of $I_{P \max}$	< 1	$\mu$ s
$di/dt$	$di/dt$ accurately followed	> 200	A/ $\mu$ s
$f$	Frequency bandwidth (- 1 dB)	DC .. 200	kHz

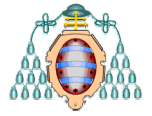


$$S = \frac{1}{1+DG} \quad T = \frac{DG}{1+DG} = S \cdot DG$$



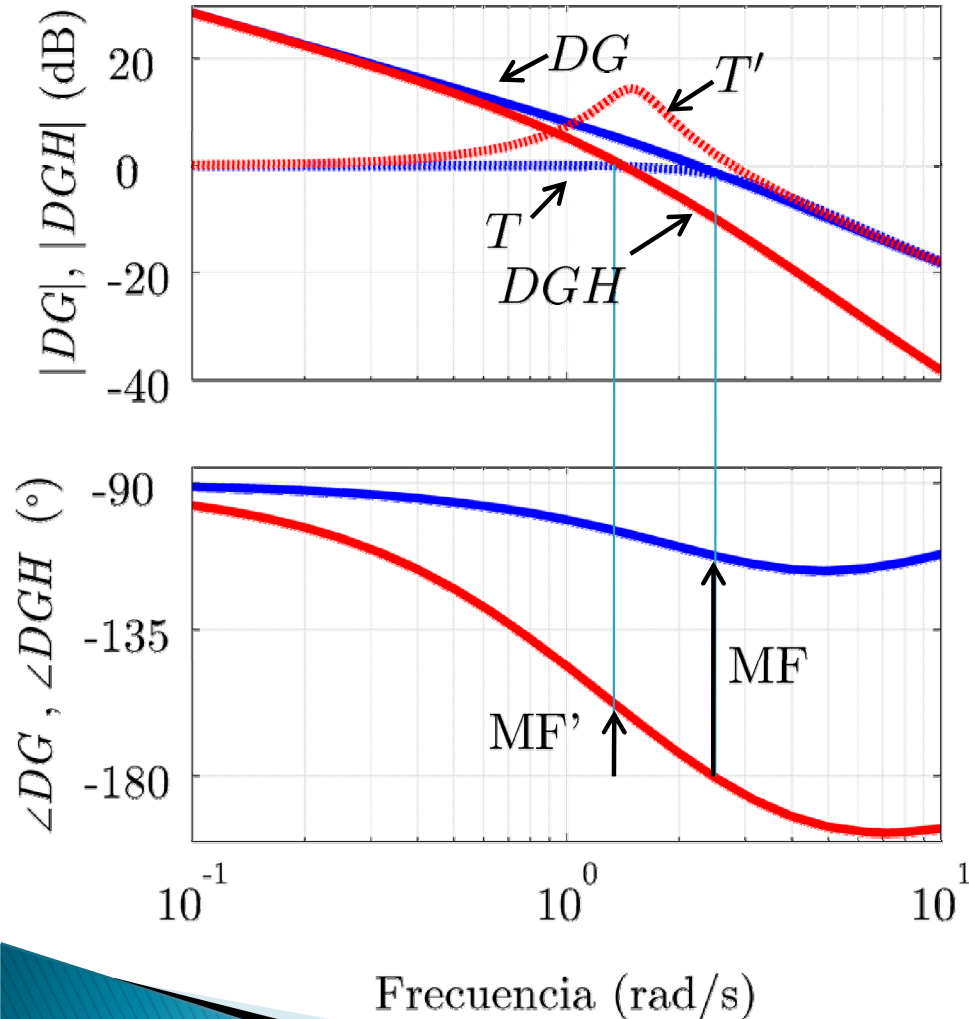
$$S' = \frac{1}{1+DGH} \quad T' = \frac{DG}{1+DGH} = S' \cdot DG$$





# Respuesta dinámica

Efecto de un sensor con dinámica lenta



Si el ancho de banda del sensor real no es mucho mayor que el ancho de banda del sistema realimentado con sensor ideal:

- El ancho de banda apenas se modifica
- Disminuye la estabilidad relativa
- Más sensibilidad
- Más oscilación
- Mayor tiempo de establecimiento